

33 ΒΑΘΜΟΛΟΓΙΚΟ - ΧΑΛΑΝΔΡΙ

ΕΝΔΕΙΚΤΙΚΕΣ ΑΠΑΝΤΗΣΕΙΣ ΦΥΣΙΚΗΣ ΚΑΤΕΥΘΥΝΣΗΣ

ΘΕΜΑ Α. , A₁ γ A₂ β A₃ γ ή β A₄ β A₅. Σ Σ Λ Λ Σ (4×5+5×1)=25

ΘΕΜΑ Β.

B₁ iii

$$\begin{array}{l}
 \text{A. Δ. Ο } m_1 v_{1\max} = (m_1 + m_2) v_{2\max} \Rightarrow v_{1\max} = 2v_{2\max} \quad (2) \\
 v_{\max} = \omega A \quad (2) \\
 \omega = \sqrt{k/m} \quad (1) \\
 \omega_1 = \omega_2 \quad (1+1) \\
 \omega_1 A_1 = 2\omega_2 A_2 \Rightarrow A_1/A_2 = 2 \quad (1)
 \end{array}
 \left. \vphantom{\begin{array}{l} \\ \\ \\ \\ \end{array}} \right\} 6 \left. \vphantom{\begin{array}{l} \\ \\ \\ \\ \end{array}} \right\} 8$$

B₂ ii

$$\begin{array}{l}
 T_S = f_1 - f_2 \Rightarrow \frac{1}{T_S} = f_1 - f_2 \Rightarrow f_1 - f_2 = 0,5 \text{ Hz} \quad (1) \quad (2) \\
 \Sigma \epsilon 2 \text{ s } 200 \text{ ταλ/δευτ, άρα } \bar{f} = 100 \text{ Hz} \quad (1) \\
 \bar{f} = \frac{f_1 + f_2}{2} \Rightarrow f_1 + f_2 = 200 \text{ Hz} \quad (2) \quad (2) \\
 \text{Από } (1) \wedge (2) : 2f_1 = 200,5 \text{ Hz} \Rightarrow f_1 = 100,25 \text{ Hz} \quad (1)
 \end{array}
 \left. \vphantom{\begin{array}{l} \\ \\ \\ \end{array}} \right\} 6 \left. \vphantom{\begin{array}{l} \\ \\ \end{array}} \right\} 8$$

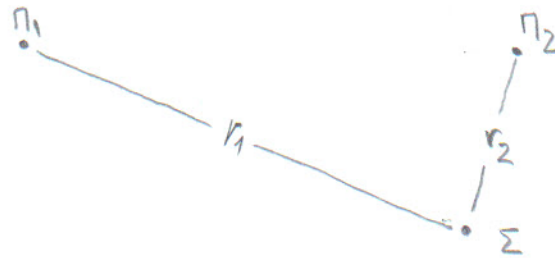
(25)

B₃ iii

$$\begin{array}{l}
 \text{Απόσταση σταθερή: } \vec{v}'_1 = \vec{v}''_2 \quad (2) \\
 \text{Η } m_2 \text{ μετά την κρούση έχει } \vec{v}''_2 = -\vec{v}'_2, \text{ άρα } \vec{v}'_1 = -\vec{v}'_2 \quad (1) \\
 \text{Κρούση κεντρική ελαστική: } v_1' = \frac{m_1 - m_2}{m_1 + m_2} v_1, v_2' = \frac{2m_1 v_1}{m_1 + m_2} \quad (2) \\
 \frac{m_1 - m_2}{m_1 + m_2} v_1 = -\frac{2m_1 v_1}{m_1 + m_2} \Rightarrow \frac{m_1}{m_2} = \frac{1}{3} \quad (2)
 \end{array}
 \left. \vphantom{\begin{array}{l} \\ \\ \\ \end{array}} \right\} 7 \left. \vphantom{\begin{array}{l} \\ \\ \end{array}} \right\} 9$$

ΘΕΜΑ Γ

2/4



Γ1. Απο

Γ1. Ανοχώνηση χρόνων $t_2 = 0,25$, $t_1 = 1,45$ (1+1) (2)
 $v_2 = v t_2 = 5 \frac{m}{s} \cdot 0,25 \Rightarrow v_2 = 1m$ (2)
 $v_1 = v \cdot t_1 = 5 \frac{m}{s} \cdot 1,45 \Rightarrow v_1 = 7m$ (2)

Γ2. Από σχήμα $3T = 1,45 - 0,25 \Rightarrow T = 0,4$ (1)
 $v = \lambda f \Rightarrow \lambda = vT = 5 \frac{m}{s} \cdot 0,4s \Rightarrow \lambda = 2m$ (1)
 $y_\Sigma = 0$ $0 \leq t < 0,25$ (1)
 $y_\Sigma = 5 \cdot 10^{-3} \cdot \eta \mu \alpha \rho \eta (2,5t - \frac{1}{2})$ (CSJ), $0,25 \leq t < 1,45$ (1)
 $y_\Sigma = 2A \cdot 6\omega \frac{\alpha \eta (r_1 - r_2)}{2\lambda} \cdot \eta \mu \alpha \rho \eta (\frac{t}{T} - \frac{v_1 + v_2}{2\lambda}) = -10 \cdot 10^{-3} \cdot \eta \mu \alpha \rho \eta (2,5t - 2)$ (CSJ) $1,45 \leq t \leq 2,25$ (2)

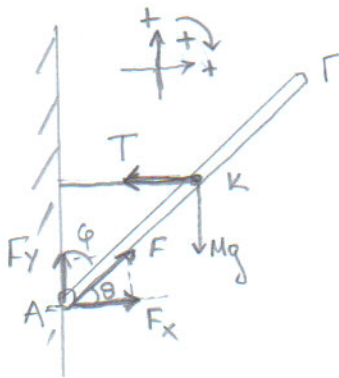
(25)

Γ3 Α.Δ.Ε. για μη ταλάντωση: $\frac{1}{2} D y_1^2 + \frac{1}{2} m v_1^2 = \frac{1}{2} D A^2 \Rightarrow$ (3)
 $v_1 = \pm \omega \sqrt{A^2 - y_1^2} = \pm \frac{2\eta}{0,4} \sqrt{(10 \cdot 10^{-3})^2 - (5\sqrt{3} \cdot 10^{-3})^2} \frac{m}{s} \Rightarrow$ (2)
 $v_1 = 25\pi \cdot 10^{-3} \frac{m}{s}$ ή $v_1 = \frac{\pi}{40} m/s$ (1)

Γ4 $\frac{K_{1max}}{K_{2max}} = \frac{E_1}{E_2} = \frac{\frac{1}{2} D_1 A_1^2}{\frac{1}{2} D_2 A_2^2} = \frac{m \omega_1^2 A_1^2}{m \omega_2^2 A_2^2} \Rightarrow \frac{K_{1max}}{K_{2max}} = \frac{f_1^2 A_1^2}{f_2^2 A_2^2}$ (2)
 $v = \lambda_1 f_1 = \lambda_2 f_2 \Rightarrow \frac{\lambda_1}{\lambda_2} = \frac{f_2}{f_1} = \frac{10}{9} \Rightarrow \lambda_2 = \frac{9}{10} \lambda_1$ (1)
 $A_2 = 2A \cdot \left| 6\omega \frac{\alpha \eta (r_1 - r_2)}{2\lambda_2} \right| = 2A \cdot \left| 6\omega \frac{60\eta}{18} \right| = 2A \cdot 6\omega \frac{\eta}{3} \Rightarrow A_2 = A = A_1/2$ (2)
 $\frac{K_{1max}}{K_{2max}} = \frac{f_1^2 \cdot A_1^2}{(\frac{10}{9} f_1)^2 \cdot (\frac{A_1}{2})^2} = 4 \cdot \frac{81}{100} \Rightarrow \frac{K_{1max}}{K_{2max}} = \frac{81}{25} = 3,24$ (2)

ΘΕΜΑ Δ.

Δ1



$$\Sigma F_y = 0 \Rightarrow F_y - Mg = 0 \Rightarrow F_y = 56 \text{ N}, \quad +\Sigma x \dot{\mu} \alpha \quad (1)$$

$$\Sigma F_x = 0 \Rightarrow F_x - T = 0 \Rightarrow F_x = T \quad (1)$$

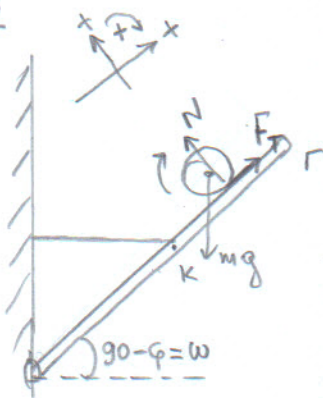
$$\Sigma \tau(A) = 0 \Rightarrow Mg \frac{l}{2} \eta \mu \varphi - T \frac{l}{2} 6 \omega \varphi = 0 \Rightarrow T = Mg \frac{\eta \mu \varphi}{6 \omega \varphi} \Rightarrow T = 42 \text{ N}$$

$$\text{Από } (1) \Rightarrow F_x = 42 \text{ N} \quad (1)$$

$$F = \sqrt{F_x^2 + F_y^2} = \sqrt{42^2 + 56^2} \text{ N} \Rightarrow F = 70 \text{ N} \quad (1)$$

$$\epsilon \varphi \vartheta = \frac{F_y}{F_x} = \frac{56}{42} \Rightarrow \epsilon \varphi \vartheta = \frac{4}{3} \quad (1)$$

Δ2



$$\Sigma F_x = m a_{cm} \Rightarrow F_T - mg \cdot 6 \omega \varphi = m a_{cm} \quad (1)$$

$$\Sigma \tau = I \cdot \alpha_{\text{γων}} \Rightarrow -T \cdot r = I \cdot \alpha_{\text{γων}} \quad (1)$$

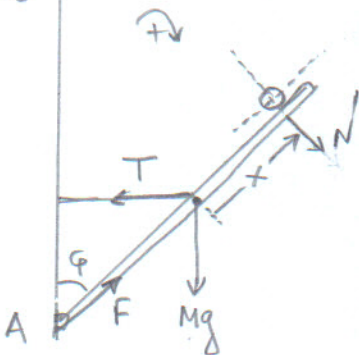
$$a_{cm} = \alpha_{\text{γων}} \cdot r \quad + \Sigma x \dot{\mu} \alpha \quad (1)$$

Ο συνδυασμός τους δίνει

$$a_{cm} = - \frac{g \cdot 6 \omega \varphi}{1 + \frac{2}{5}} = - \frac{10 \cdot 0,8}{1 + \frac{2}{5}} \text{ m/s}^2 \Rightarrow a_{cm} = - \frac{40}{7} \text{ m/s}^2 \quad (2)$$

$$\alpha_{\text{γων}} = \frac{a_{cm}}{r} = \frac{-40/7}{1/70} \text{ rad/s}^2 \Rightarrow \alpha_{\text{γων}} = -400 \text{ rad/s}^2$$

Δ3



$$\text{Η } N' \text{ προέρχεται από τη σφαίρα, } N' = mg \eta \mu \varphi$$

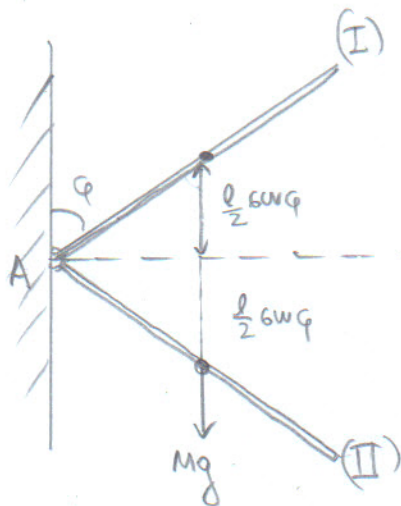
$$\Sigma \tau(A) = 0 \Rightarrow Mg \frac{l}{2} \eta \mu \varphi - T \frac{l}{2} 6 \omega \varphi + N' \left(\frac{l}{2} + x \right) = 0 \Rightarrow (3)$$

$$T = \frac{Mg \frac{l}{2} \eta \mu \varphi + mg \eta \mu \varphi \left(\frac{l}{2} + x \right)}{\frac{l}{2} \cdot 6 \omega \varphi} = \frac{Mg \eta \mu \varphi + mg \eta \mu \varphi (1+x)}{6 \omega \varphi} \quad (2)$$

$$\Rightarrow T = \frac{56 \cdot 0,6 + 4 \cdot 9,6 (1+x)}{0,8} \Rightarrow T = 45 + 3x \text{ (SI)} \quad (2)$$

με $0 \leq x \leq 1 \text{ m}$

Δ4



$$\frac{dK}{dt} = \Sigma \tau \cdot \omega \quad (1)$$

$$\Sigma \tau = Mg \frac{l}{2} \eta \mu \varphi = 56 \cdot \frac{2}{2} \cdot 0,6 \text{ Nm} \Rightarrow \Sigma \tau = 33,6 \text{ Nm} \quad (1)$$

$$E_{\text{μηχ}}(I) = E_{\text{μηχ}}(II) \Rightarrow$$

$$U=0 \quad -Mg \frac{l}{2} \sin \varphi + 0 = -Mg \frac{l}{2} \cos \varphi + \frac{1}{2} I_A \omega^2 \Rightarrow \quad (2)$$

$$2Mg \frac{l}{2} \sin \varphi = \frac{1}{2} \cdot \frac{1}{3} M l^2 \omega^2 \Rightarrow \omega = \sqrt{\frac{6 \cdot g \sin \varphi}{l}} \Rightarrow \quad (1)$$

$$\omega = \sqrt{\frac{6 \cdot 10 \cdot 0,6}{2} \frac{\text{r}}{\text{s}}} \Rightarrow \omega = 2\sqrt{6} \text{ r/s}$$

Αρτιακά στοιχεία σπιν (1)

$$\frac{dK}{dt} = 33,6 \cdot 2\sqrt{6} \frac{\text{J}}{\text{s}} = 67,2\sqrt{6} \frac{\text{J}}{\text{s}} = \frac{336\sqrt{6}}{5} \frac{\text{J}}{\text{s}} \quad (1)$$

Διατ. έργου-υπολ. ω (3)
 πίνος $\frac{dK}{dt}$ (1)
 εύρεση $\Sigma \tau$ (1), ανोट. (1)

(25)

Δ5

$$\vec{L}_{O\lambda}^{\text{πιν}} = \vec{L}_{O\lambda}^{\text{μετά}} \Rightarrow I_{(A)} \omega = I_{O\lambda(A)} \cdot \omega' \Rightarrow \quad (1)$$

$$I_{O\lambda(A)} = \frac{1}{3} M l^2 + \frac{1}{3} 3 M l^2 \Rightarrow I_{O\lambda(A)} = \frac{4}{3} M l^2 = 4 I_{(A)} \quad (1)$$

$$\omega' = \frac{\frac{1}{3} M l^2 \omega}{\frac{4}{3} M l^2} \Rightarrow \omega' = \frac{\omega}{4} \Rightarrow \omega = \frac{\sqrt{6}}{2} \text{ r/s} \quad (1)$$

$$\frac{|\Delta K|}{K_{\text{αρχ}}} 100\% = \frac{|\frac{1}{2} I_{O\lambda} \omega'^2 - \frac{1}{2} I \omega^2|}{\frac{1}{2} I \omega^2} 100\% = \left| \left(\frac{I_{O\lambda}}{I} \frac{\omega'^2}{\omega^2} - 1 \right) \right| 100\% \Rightarrow \quad (2)$$

$$\frac{|\Delta K|}{K_{\text{αρχ}}} 100\% = \left| 4 \frac{\omega^2/16}{\omega^2} - 1 \right| 100\% = \left| \frac{1}{4} - 1 \right| 100\% \Rightarrow \frac{|\Delta K|}{K_{\text{αρχ}}} 100\% = 75\%$$

πίνος $\frac{|\Delta K|}{K_{\text{αρχ}}} 100\%$ (1)
 εύρεση $\omega' = \frac{\sqrt{6}}{2} \text{ r/s}$ 3 (1 Διατ. σφρ + 1 εύρ. $I_{O\lambda}$ + 1 πράξη)
 τριμικέλιξη φφρ. μοτιά γέμα (1)

ΣΥΝΤΟΝΙΣΤΕΣ : ΠΑΛΟΓΟΣ ΑΝΤΩΝΗΣ - ΠΛΑΚΙΑΣ ΒΑΣΙΛΗΣ